

## **Optimisation**

# Introducing

#### Description

Program (detailed contents):

- Elements of convex analysis: convexity, lower semicontinuity, notion of subdifferential, elements of analysis for algorithmic purposes (Lipschitz gradient functions, strong convexity, conditioning)
- Optimality conditions (Karush Kuhn Tucker conditions, second order sufficient conditions)
- Lagrangian duality
- Algorithms for unconstrained differentiable optimization and link with ODEs: generalities on descent methods, gradient algorithms, Newton and quasi-Newton algorithms. Convergence study and convergence speed depending on the geometry of the functions to be minimized.
- Algorithms for constrained differentiable optimization: SQP, penalization methods, augmented Lagrangian.
- Convex optimization: how convexity can improve the convergence speed of algorithms.
- Inertial algorithms, Nesterov acceleration. Subgradient algorithms. Notion of proximal operator, Moreau regularization, proximal algorithms. Splitting methods: Forward Backward algorithm and Nesterov acceleration (FISTA). Study of convergence and convergence rate on the class of convex functions.

#### **Objectives**

At the end of this module, the student will have understood and be able to explain (main concepts):

- \* Existence and uniqueness conditions for solutions of an optimization problem (constrained differentiable optimization, non-differentiable convex optimization)
- \* Optimality conditions: Karush Kuhn Tucker points in the constrained differentiable case, optimality NHA in unconstrained convex optimization.
- \* The duality principle: Lagrangian duality, Fenchel-Rockafellar duality
- \* Gradient and Newton type algorithms, and their convergence results, classical algorithms of constrained optimization:
- \* The general principle of inertial algorithms: acceleration of gradient algorithms, generalization to the composite case.

The student will be able to:

- Interpret the behavior of an algorithm as a discretization of a dynamic system
- Identify classes of optimization problems and propose algorithms adapted to the geometry of the functions to be minimized.
- Implement and numerically calibrate these algorithms.

#### Necessary prerequisites

Basics of differential calculus and linear algebra.





3rd year MIC optimization course

#### Évaluation

L'évaluation des acquis d'apprentissage est réalisée en continu tout le long du semestre. En fonction des enseignements, elle peut prendre différentes formes : examen écrit, oral, compte-rendu, rapport écrit, évaluation par les pairs...

# Practical info

### Location(s)

Toulouse

