

Service Robotics



ECTS
6 crédits



Hourly volume
50h

 Toulouse

Introducing

Objectives

At the end of this module, the student would be able to explain the main components of a robot service and to say in which way it differs from industrial robotics; he/she will know the main concepts in humanoid robotics and why it is difficult to control a walking robot. His/her knowledge will include the main notions in jointed robotics: direct and inverse kinematic models, dynamic model of the robot, trajectory generation and stability of a bipedal robot.

The student is supposed to be able to model a jointed robot, to understand its technical components and to analyse the functioning of a service robot in its domestic or professional environment.

Necessary prerequisites

Matrix theory, Linear control

Practical info

Location(s)